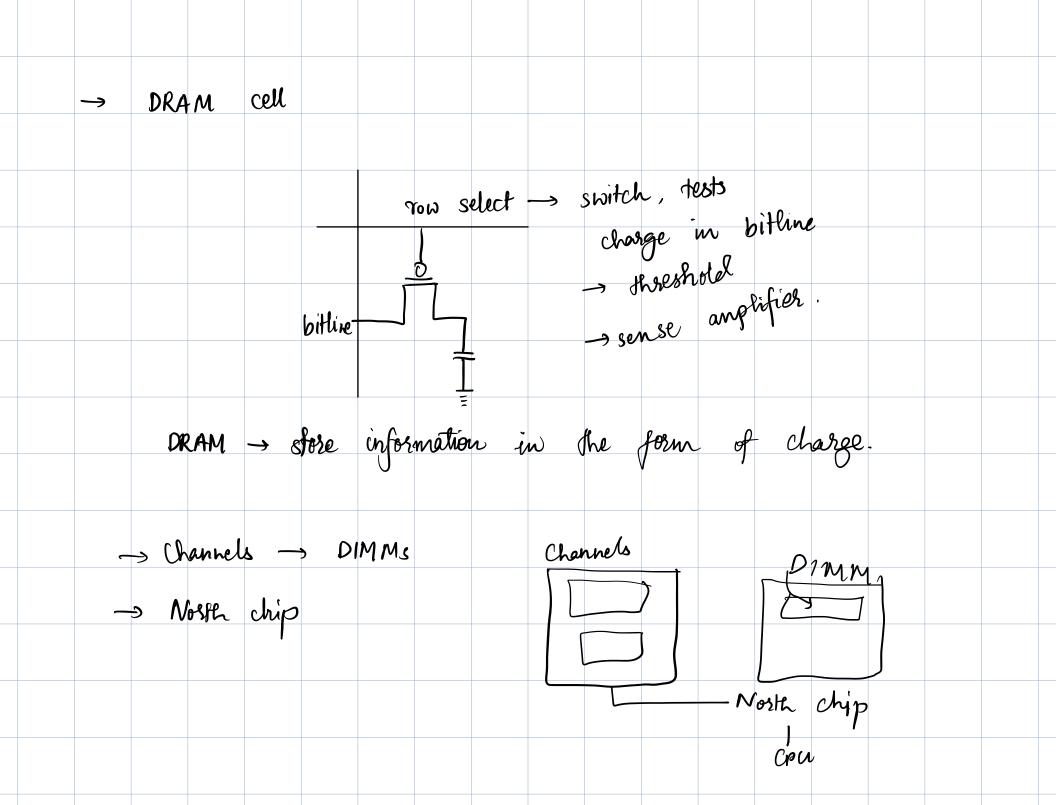
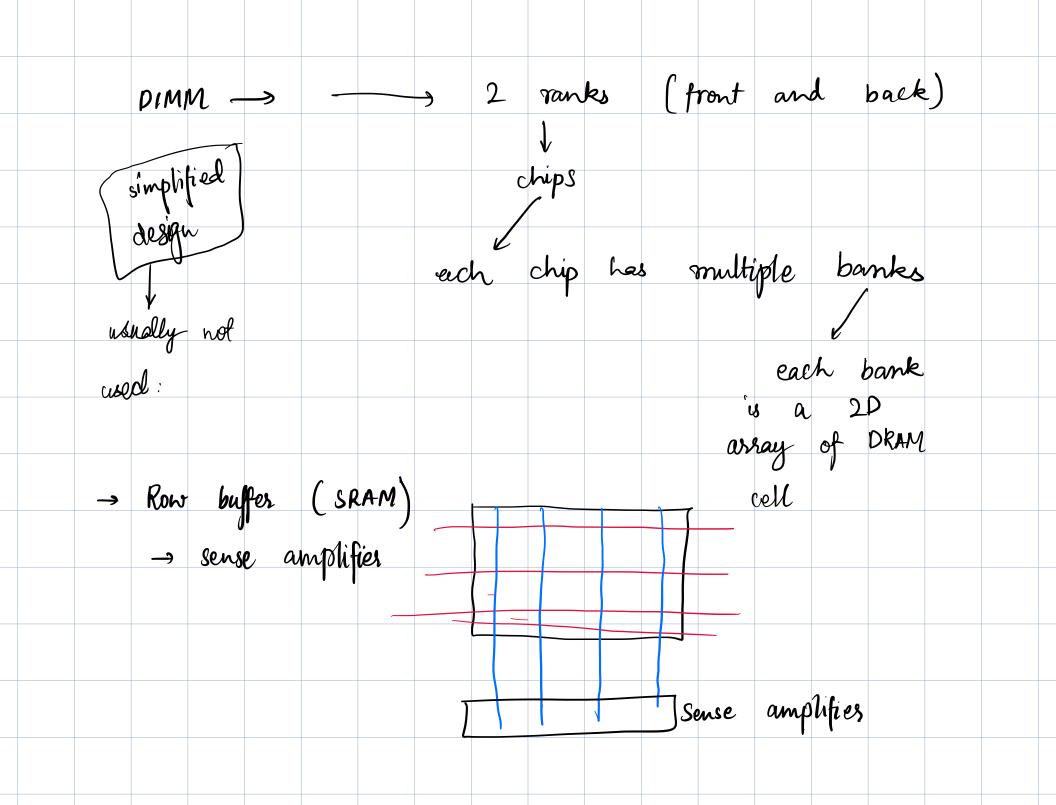
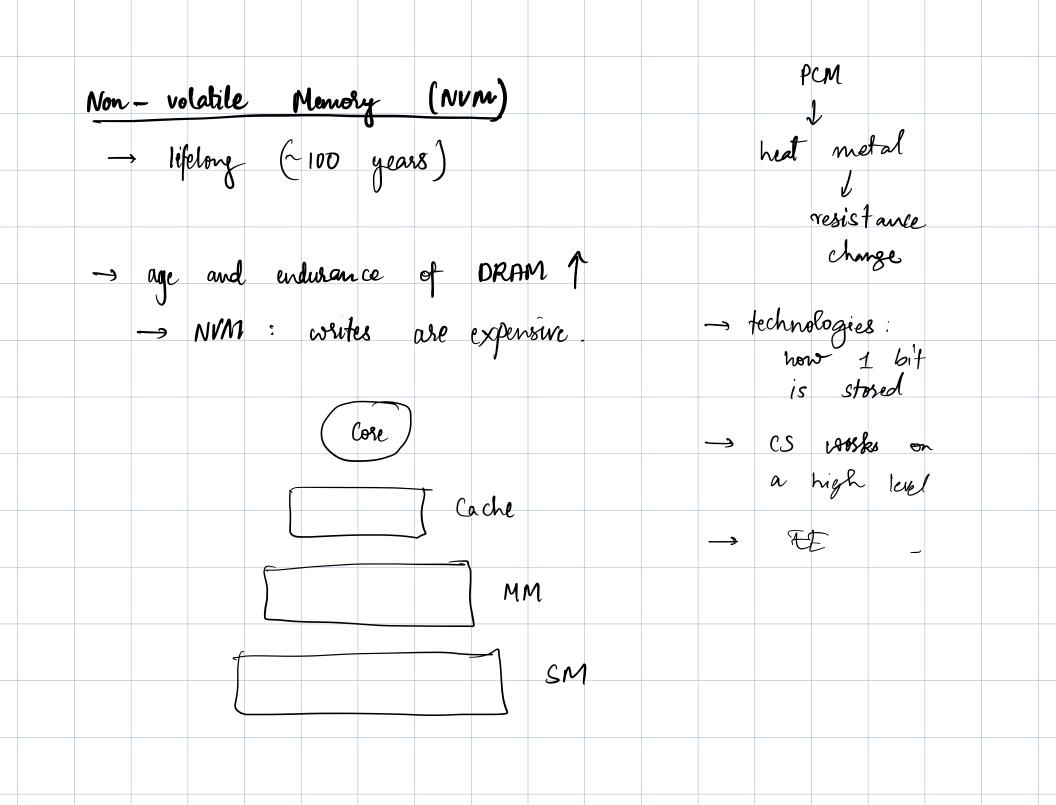
11 Feb 2025 - DBMS-II - Week OG Introduction to Memory Management -> Hard disks ~> obsolete -> Pen drives → RAM von newmann 0 architectuse memory -> CPU nard disk Why RAM/cache? -> Memory technology: what technology is used to store -> spatial & temposal 1 bit of information ? locality





-> ORAM used in memory -> information is stored in terms of charge -> needs periodic refreshment Ly research in reduction is active ache main men flash magnetic disk optical disk (CO/OVD) magnetic tapes ~> cassettes

Disadvantage of SRAM and DRAM SRAM\_ DRAM -> density V -> destructive read operation -> veguires periodic refresh to restore data -> 6 transistors -> high leakage -> Hugh leakage power consumption -> volatile memory as compared to offrer main menn tech. embedded > eDRAM of discharge  $\rightarrow$  Ofher menn tech.  $\rightarrow$  being explosed Jache SRAM [Gache SRAM] other Menoy pram)other -> Magneto Resistive RAM Memory ORAM -> Spin - Transfer Torgue RAM -> Phase - change memory (pcm) Hybsid



2025 - 02 - 15 storage and file Structure 10.2.3 → read once not cache block but page → block, page -> secondary memory to main memory -> every relation is stored in a file always a page multiple rows form a block. is fetched each row is called a record -> RAID : redundant array of independent disk invented during disk times  $\rightarrow$  modified versions today

Main requirements for database storage in disk: ① reliability: disk failure, power problems etc should not affect my data. -> solved using redundancy / mirroring → cost 1 disk size↓ 200GB 7 → effective available } 100GB -> in last chapter, we removed redundancies within the database but maintaining only 1 copy of redundant -free data is not reliable.

Ì Performance -> parallelism : reading multiple stuff. → data stripping 100 R → transfer rate can be less ( both reguests on 50R 50R same DB) but bandwidth 1 -> record interleaved stripping

Reliability and performance of Storage <sup>></sup> Data skipping Replication -> Bit - interleaved -> Mirroring Block - interleaved -> Error correcting codes (ECC) -> to read a block you need to read -> tamming cooles al disks: not efficient BIR · P2. > Parity bits parellelism -> cannot detect 2 or even changes -> cannot detect where exactly I networks error happened -, use Mammy codes

 $\left(\begin{array}{c} \\ 0 \\ 1 \end{array}\right)$  $\times$ parity - Assumption: only one disk fails at a time -> Diffesence 6/20 this and netroosking: you know which DB malfunctioned and you can recreate it easily Main goals of parallelism: @ Load-balance small accesses (block accesses) 2 parallelise large accesses so that 20 that throughput of the response time is I such accessis t

